

PREVIEW to:

**Covering Arrays: Evaluating
 t -Coverage & t -Diversity in the
presence of disallowed
combinations**

ITEA 2018

6th Cyber Security Workshop

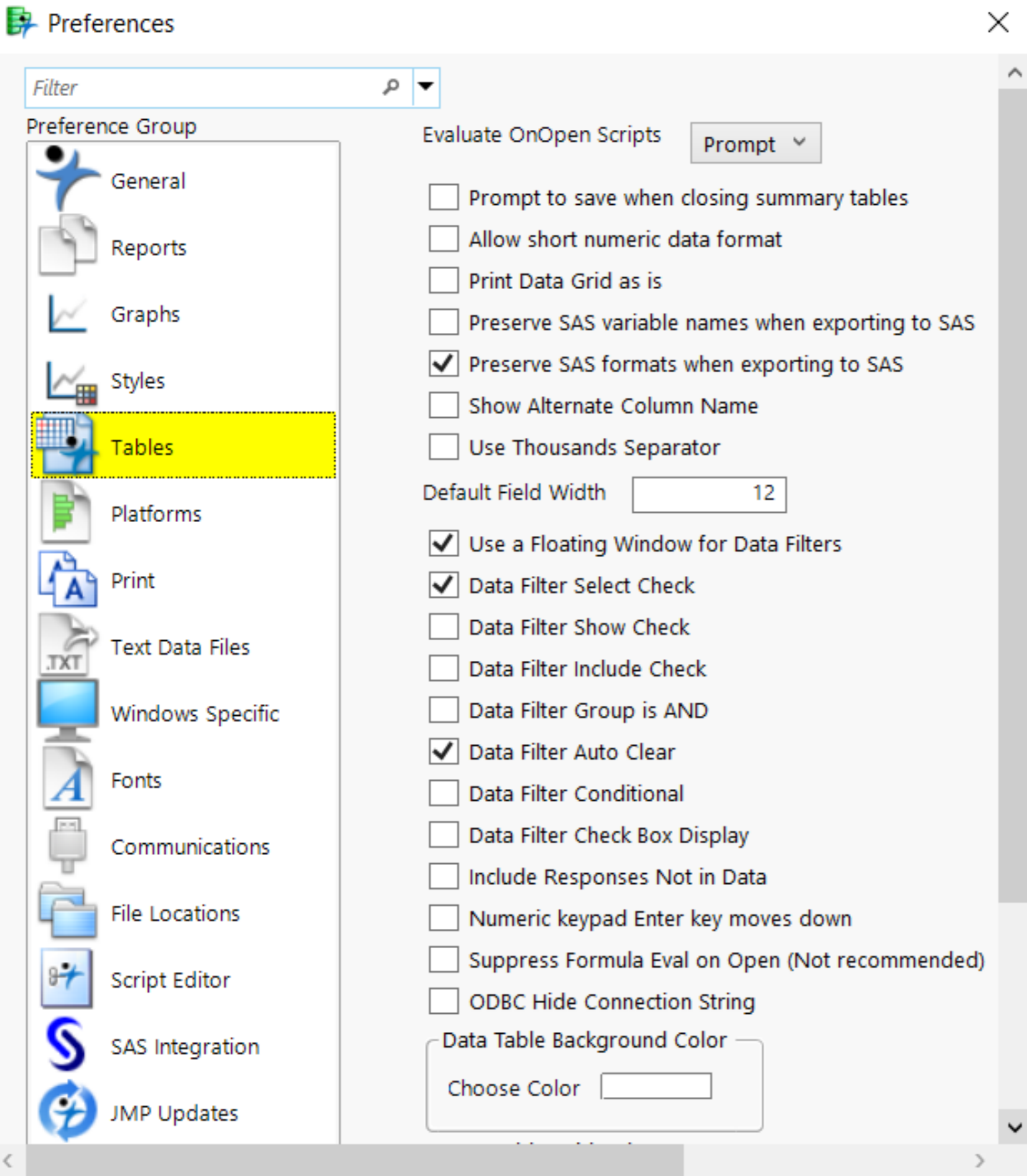
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Twenty check boxes in this dialog box

$2^{20} = 1,048,576$ possible combinations

How many tests to check:

All pairs?

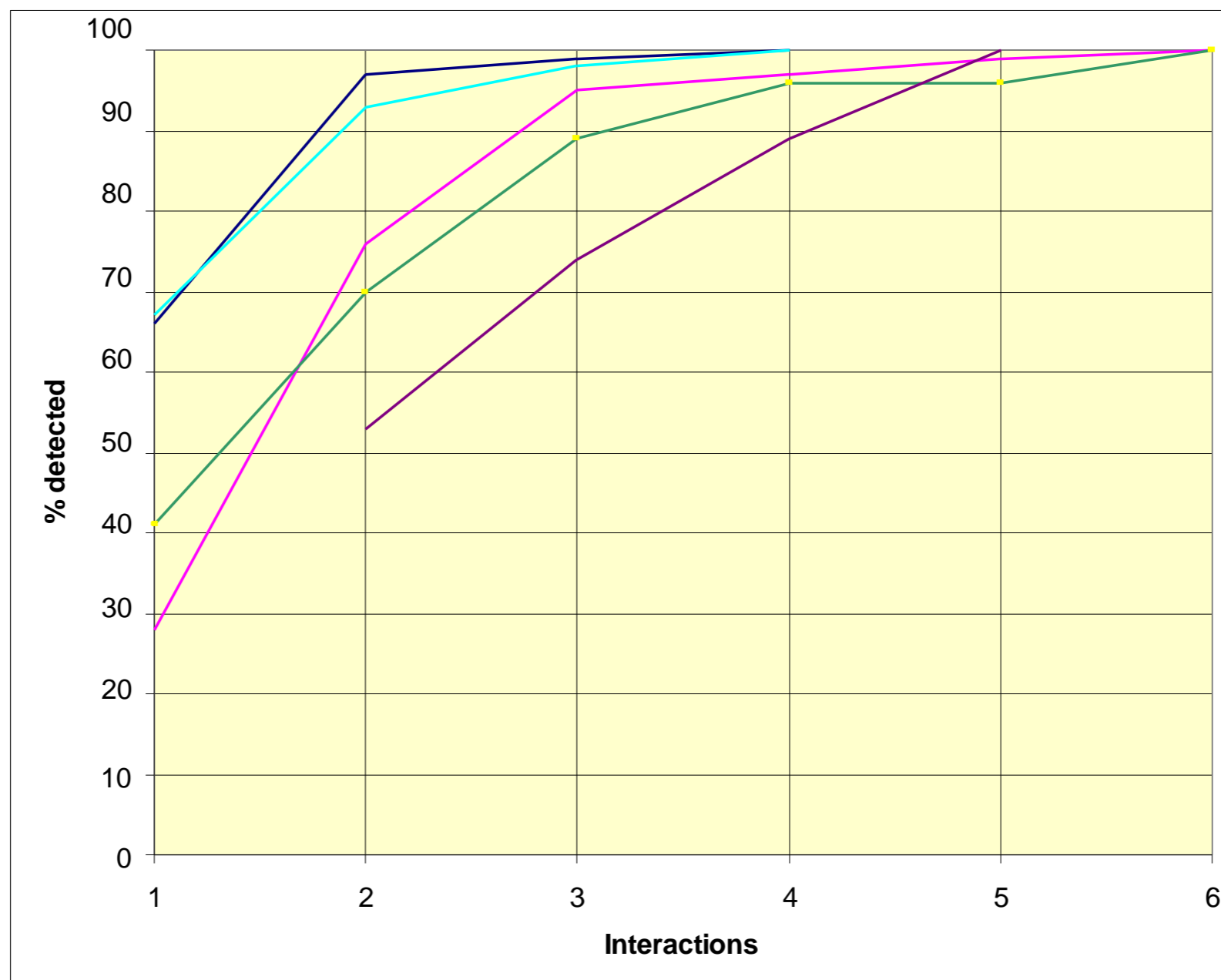
All triples?

All quadruples?

All quintuples?

All sextuples?

Traffic Collision Avoidance System module (seeded errors) (purple)



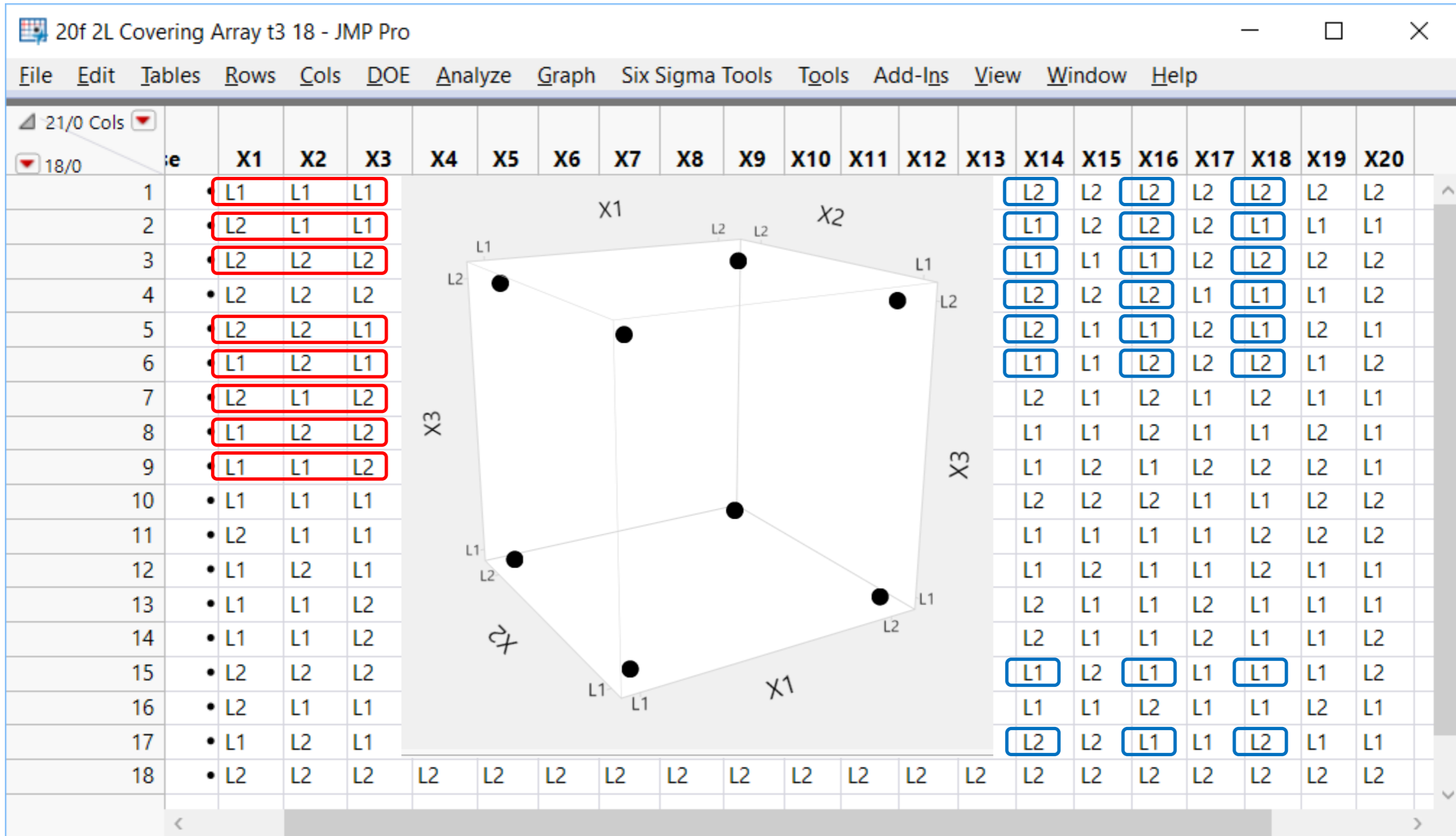
So, how many parameters are involved in really tricky faults?

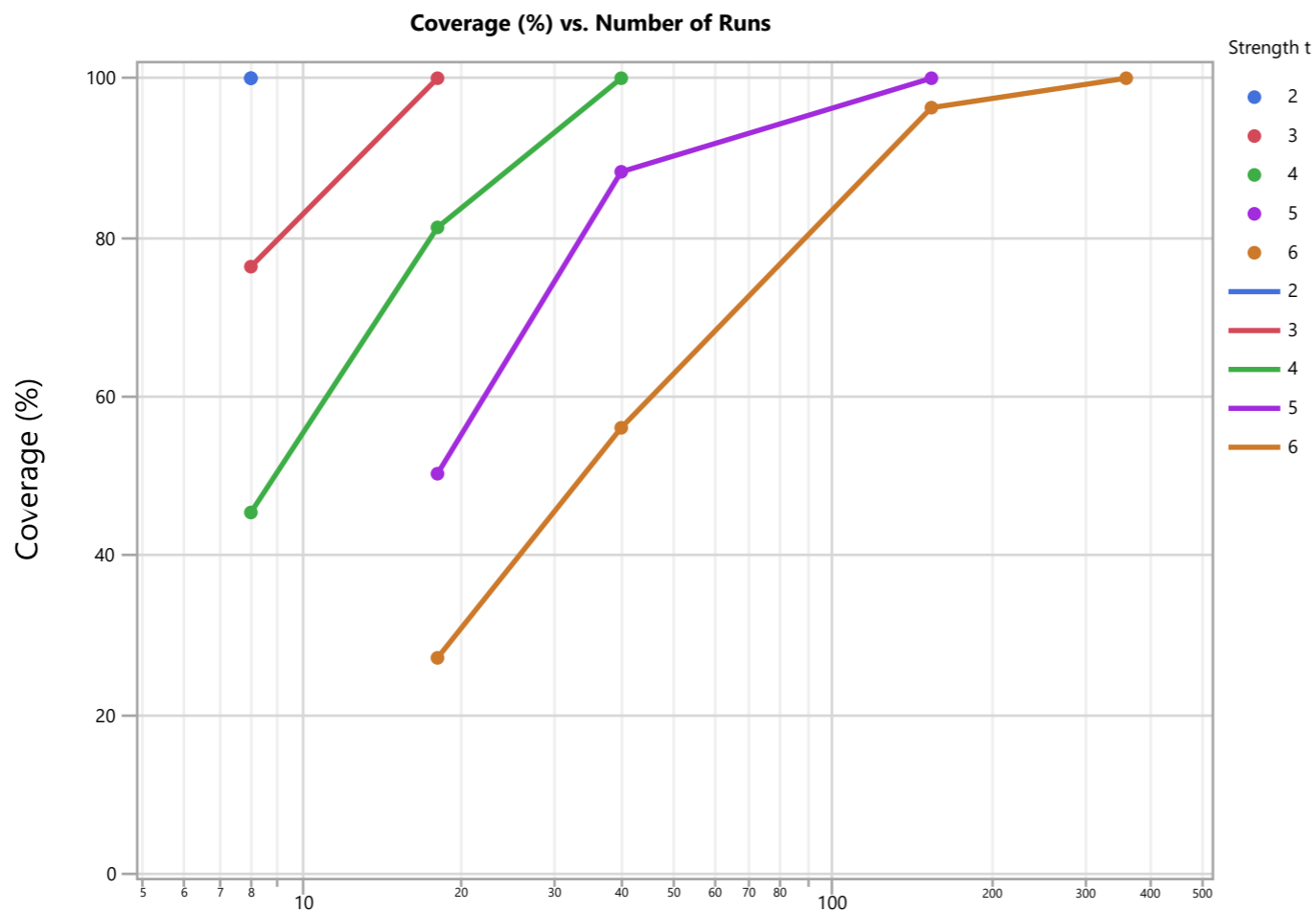
- **Maximum interactions** for fault triggering for these applications was **6**
- Much more empirical work needed
- Reasonable evidence that maximum interaction strength for fault triggering is **relatively small**

How does it help me to know this?



All triples in only 18 tests, covering $\binom{20}{3} 2^3 = 9,120$ combinations





Metrics

Number of Runs: 8

t	Coverage	Diversity
2	100.00	50.00
3	76.32	76.32
4	45.43	90.87

Metrics

Number of Runs: 18

t	Coverage	Diversity
3	100.00	44.44
4	81.25	72.22
5	50.30	89.42
6	27.16	96.57

Metrics

Number of Runs: 40

t	Coverage	Diversity
4	100.00	40.00
5	88.24	70.59
6	56.07	89.71

Metrics

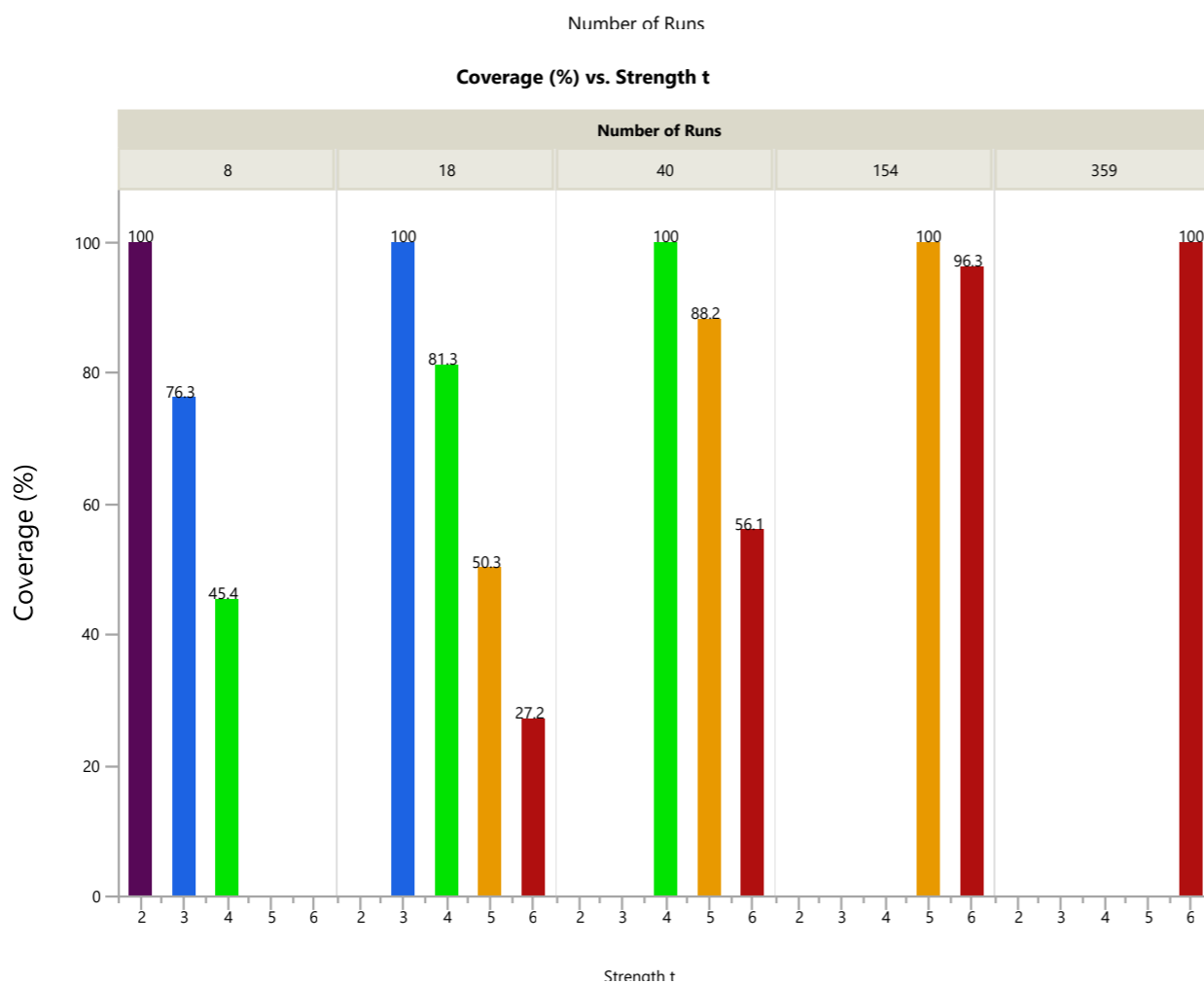
Number of Runs: 154

t	Coverage	Diversity
5	100.00	20.78
6	96.39	40.06

Metrics

Number of Runs: 359

t	Coverage	Diversity
6	100.00	17.83



Traffic Collision Avoidance System (TCAS)

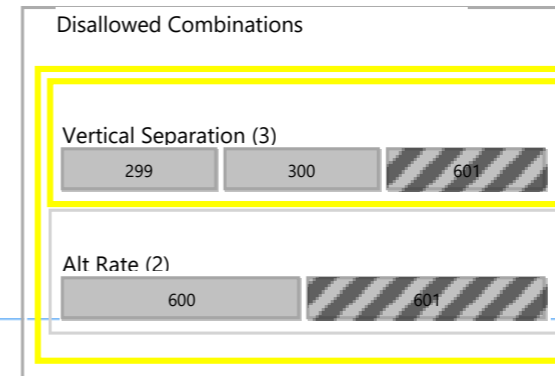
$2^7 3^2 4^1 10^2 = 460,800$ possible combinations

The screenshot shows the JMP Pro interface with a table titled 'TCAS Factors'. The table has 13 columns: Vertical Separation, High Confidence, 2 of 3 Valid, Own Tracked, Other Tracked, Alt Rate, Alt Layer, Up Separation, Down Separation, Other RAC, Other Capability, and Climb Inhibit. The 'Alt Rate' column has a value of 601 in row 2, which is circled in red. A red line connects this value to the '601' value in the 'Vertical Separation' column of row 3, which is also circled in red. A dialog box titled 'Disallowed Combinations' is overlaid on the table, showing two sections: 'Vertical Separation (3)' with values 299, 300, and 601 (the 601 is shaded with diagonal lines), and 'Alt Rate (2)' with values 600 and 601 (the 601 is shaded with diagonal lines).

	Vertical Separation	High Confidence	2 of 3 Valid	Own Tracked	Other Tracked	Alt Rate	Alt Layer	Up Separation	Down Separation	Other RAC	Other Capability	Climb Inhibit
1	299	True	True	1	1	600	0	0	0	No Intent	TCAS	True
2	300	False	False	2	2	601	1	399	399	Do not climb	Other	False
3	601						2	400	400	Do not descend		
4							3	499	499			
5								500	500			
6								639	639			
7								640	640			
8								739	739			
9								740	740			
10								840	840			

**Certain combinations of settings are not allowed.
e.g. Vertical Separation = 601 and Alt Rate = 601.**

Sorted Covering Array has 100 rows, first 20 showing Vertical Separation = 601 and Alt Rate \neq 601



	Response	Vertical Separation	High Confidence	2 of 3 Valid	Own Tracked	Other Tracked	Alt Rate	Alt Layer	Up Separation	Down Separation	Other RAC	Other Capability	Climb Inhibit
1		• 601	True	True	2	2	600	3	499	640	No Intent	TCAS	False
2		• 601	False	True	2	1	600	3	640	739	No Intent	TCAS	True
3		• 601	False	True	1	2	600	3	499	399	No Intent	Other	False
4		• 601	False	True	2	1	600	1	500	639	Do not climb	Other	False
5		• 601	False	False	1	1	600	0	400	500	Do not climb	Other	True
6		• 601	True	False	1	1	600	3	0	400	No Intent	TCAS	True
7		• 601	True	True	1	2	600	3	639	740	Do not descend	TCAS	False
8		• 601	False	False	1	2	600	0	399	500	No Intent	TCAS	False
9		• 601	False	False	1	1	600	1	640	399	Do not descend	TCAS	True
10		• 601	True	False	2	1	600	0	739	499	Do not climb	Other	False
11		• 601	False	False	2	2	600	2	399	740	Do not climb	TCAS	False
12		• 601	False	True	1	2	600	2	739	500	No Intent	Other	False
13		• 601	False	False	2	1	600	1	0	639	Do not climb	TCAS	False
14		• 601	False	True	1	2	600	2	740	739	Do not descend	Other	False
15		• 601	True	True	1	1	600	1	740	399	No Intent	Other	True
16		• 601	False	False	2	2	600	0	840	840	Do not descend	TCAS	False
17		• 601	True	False	1	2	600	3	840	639	Do not climb	TCAS	True
18		• 601	True	False	1	2	600	1	740	840	Do not descend	Other	False
19		• 601	True	False	1	2	600	3	499	0	Do not descend	Other	True
20		• 601	True	False	1	2	600	1	739	740	Do not descend	TCAS	False
21		• 300	False	False	1	2	601	1	739	0	Do not descend	Other	True
22		• 300	False	True	1	2	601	1	740	0	Do not descend	Other	True
23		• 300	True	True	1	2	601	3	500	0	No Intent	TCAS	False
24		• 300	True	True	1	2	601	3	500	0	No Intent	TCAS	False

Analysis of TCAS Covering Array

2 faults in 1203 run strength 4 design

Summary

Success Runs	1201
Failure Runs	2
Missing	0

Failure Analysis Details

4 Factor Interactions

Factors	Failure Levels	Failure Count
Vertical Separation, High Confidence, Up Separation, Down Separation	300, True, 399, 500	1
Vertical Separation, Own Tracked, Up Separation, Down Separation	299, 1, 499, 499	1
Vertical Separation, Alt Rate, Up Separation, Down Separation	299, 600, 499, 499	1
Vertical Separation, Alt Layer, Up Separation, Down Separation	299, 1, 499, 499	1
Vertical Separation, Alt Layer, Up Separation, Down Separation	300, 2, 399, 500	1
Vertical Separation, Up Separation, Down Separation, Climb Inhibit	300, 399, 500, False	1
High Confidence, Alt Rate, Up Separation, Down Separation	True, 601, 399, 500	1
High Confidence, Alt Layer, Up Separation, Down Separation	True, 1, 499, 499	1
High Confidence, Alt Layer, Up Separation, Down Separation	True, 2, 399, 500	1
Own Tracked, Up Separation, Down Separation, Other RAC	2, 399, 500, No Intent	1
Alt Layer, Up Separation, Down Separation, Other RAC	1, 499, 499, Do not descend	1
Alt Layer, Up Separation, Down Separation, Other RAC	2, 399, 500, No Intent	1
Alt Layer, Up Separation, Down Separation, Other Capability	2, 399, 500, TCAS	1
Alt Layer, Up Separation, Down Separation, Climb Inhibit	1, 499, 499, True	1
Alt Layer, Up Separation, Down Separation, Climb Inhibit	2, 399, 500, False	1

These 15 combinations of 4 factors associated with the two detected faults

Why Here?

- Attended 5th Cyber Security Workshop and saw little use of statistical methods, particularly design of experiments (DOE) and more specifically covering arrays.
- When analyst for the Army at Edgewood Chemical Biological Center I saw lots of “scenario based” modeling and simulation. Showed that by running a DOE covering the factor space one could include virtually any scenario in the provided analysis – efficiently.
- SAS has been using covering arrays to test its software for more than a decade as a method of quality assurance.
- I am aware of software testers at Eglin AFB and Camp Pendleton using covering arrays. There are likely others.
- I am hopeful we can excite more Cyber Security Testers to use DOE methods.

Covering Arrays: Evaluating *t*-Coverage & *t*-Diversity in the presence of disallowed combinations

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Covering arrays - Preliminaries

Definition

A *covering array* $\mathbf{CA}(N; t, k, v)$ is an $N \times k$ array such that the i -th column contains v distinct symbols. If a $\mathbf{CA}(N; t, k, v)$ has the property that for any t coordinate projection, all v^t combinations of symbols exist at least once, then it is a t -covering array (or strength t covering array). A t -covering array is optimal if N is minimal for fixed t , k , and v .

Definition

The size of a covering array is the *covering array number* $\mathbf{CAN}(t, k, v)$,

$$\mathbf{CAN}(t, k, v) = \min\{N: \exists \mathbf{CA}(N; t, k, v)\}.$$

Covering arrays - Preliminaries

Definition

Consider the covering array $A = \mathbf{CA}(N; t, k, v)$. If for any t coordinate projection of A all v^t combinations of symbols exist **exactly λ times** then A is a t -covering *orthogonal* array of index λ .

Note: Orthogonal arrays are therefore a special type of covering array.

Covering arrays - Preliminaries


1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

CA(6; 2, 5, 2)

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

CA(12; 3, 5, 2)

Covering arrays - Preliminaries



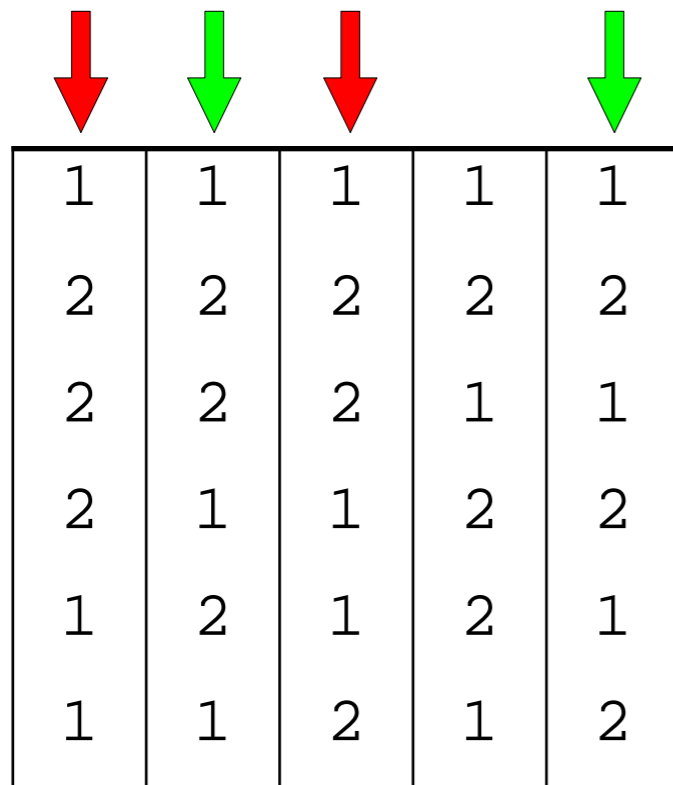
1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

CA(6; 2, 5, 2)

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

CA(12; 3, 5, 2)

Covering arrays - Preliminaries




1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

CA(6; 2, 5, 2)

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1


CA(12; 3, 5, 2)

Covering arrays - Preliminaries



1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2





CA(6; 2, 5, 2)



1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1







CA(12; 3, 5, 2)

Covering arrays - Preliminaries



1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

CA(6; 2, 5, 2)



1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

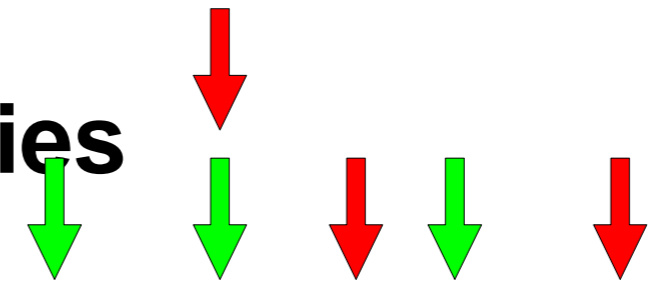
CA(12; 3, 5, 2)

Covering arrays - Preliminaries

1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

Optimal¹

CA(6; 2, 5, 2)



1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

Not optimal²
CAN = 10

CA(12; 3, 5, 2)

¹ A. Renyi, 1948

² K. Johnson & R. Entringer, 1989

Covering arrays - Software & Systems Validation

“Bugs lurk in corners and congregate at boundaries.¹”

¹B. Beizer, *Software Testing Techniques*, Van Nostrand Reinhold, 1983

Covering arrays - Software & Systems Validation

“Bugs lurk in corners and congregate at boundaries.¹”

*“...choose the type of corner and **cover** it.”*

¹B. Beizer, *Software Testing Techniques*, Van Nostrand Reinhold, 1983

Case Study #1

Air to ground missile system

Air to ground missile system

Consider a software system controlling the state of an air to ground missile system (Dalal & Mallows¹).

	Input	Type
1	Altitude	<i>continuous</i>
2	Attack angle	<i>continuous</i>
3	Bank angle	<i>continuous</i>
4	Speed	<i>continuous</i>
5	Pitch	<i>continuous</i>
6	Roll	<i>continuous</i>
7	Yaw	<i>continuous</i>
8	Ambient Temperature	<i>continuous</i>
9	Pressure	<i>continuous</i>
10	Wind Velocity	<i>continuous</i>

¹S. R. Dalal & C. L. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

Air to ground missile system

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5	Pitch	<i>continuous</i>
6	Roll	<i>continuous</i>
7	Yaw	<i>continuous</i>
8	Ambient Temperature	<i>continuous</i>
9	Pressure	<i>continuous</i>
10	Wind Velocity	<i>continuous</i>

Challenge:

We are interested in deriving test cases to effectively validate “...response during attack maneuvering.”

¹S. R. Dalal & C. L. Mallows, “Factor-covering designs for testing software,” *Technometrics*, 40(3), 1998, 234-243.

Air to ground missile system

Let the inputs be factors. If the levels are binary then the design specification is:

	Factor	Levels
1	Altitude	1, 2
2	Attack angle	1, 2
3	Bank angle	1, 2
4	Speed	1, 2
5	Pitch	1, 2
6	Roll	1, 2
7	Yaw	1, 2
8	Ambient Temperature	1, 2
9	Pressure	1, 2
10	Wind Velocity	1, 2

Air to ground missile system

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	Factor	Levels
1	Altitude	1, 2
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3	Bank angle	1, 2
4	Speed	1, 2
5	Pitch	1, 2
6	Roll	1, 2
7	Yaw	1, 2
8	Ambient Temperature	1, 2
9	Pressure	1, 2
10	Wind Velocity	1, 2

Note: With two levels per factor, the input space is $2^{10} = 1024$ points!

Air to ground missile system

Air to ground missile system

“Naive” approach:

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	2	1	2	2	2	1
2	2	2	2	1	2	1	1	1	2

Air to ground missile system

“Naive” approach:



Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	2	1	2	2	2	1
2	2	2	2	1	2	1	1	1	2

Air to ground missile system

“Naive” approach:



Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	2	1	2	2	2	1
2	2	2	2	1	2	1	1	1	2

2

1

1

2

Missing level combinations!

Air to ground missile system

“Naive” approach:



Otherwise known as an “All values testing” strategy.

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	2	1	2	2	2	1
2	2	2	2	1	2	1	1	1	2

2 1
1 2

Missing level combinations!

Air to ground missile system

Covering array approach:  

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	1	1	1	1	1	1
1	1	1	1	2	2	2	2	2	2
1	2	2	2	1	1	1	2	2	2
2	1	2	2	1	2	2	1	1	2
2	2	1	2	2	1	2	1	2	1
2	2	2	1	2	2	1	2	1	1

Air to ground missile system

Covering array approach:  

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	1	1	1	1	1	1
1	1	1	1	2	2	2	2	2	2
1	2	2	2	1	1	1	2	2	2
2	1	2	2	1	2	2	1	1	2
2	2	1	2	2	1	2	1	2	1
2	2	2	1	2	2	1	2	1	1

CA(6; 2, 10, 2)

Optimal!

Covering arrays - Preliminaries

Definition¹

Consider the covering array $\mathcal{A} = \mathbf{CA}(N; t, k, v)$. Let n_i be the number of distinct t tuples for the i^{th} projection, p_i the number of possible t tuples for the i^{th} projection, r the number of rows, and $M = \binom{K}{t}$ the number of t column projections that can be obtained from K columns.

Note: $p_i = \prod_{k=1}^t v_{f(k)}$ where $f(k)$ is the k^{th} column of the i^{th} projection.

¹S. Dalal & C. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

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$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i.$$

Note: $p_i = \prod_{k=1}^t v_{f(k)}$ where $f(k)$ is the k^{th} column of the i^{th} projection.

¹S. Dalal & C. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

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Consider the covering array $\mathcal{A} = \mathbf{CA}(N; t, k, v)$. Let n_i be the number of distinct t tuples for the i^{th} projection, p_i the number of possible t tuples for the i^{th} projection, r the number of rows, and $M = \binom{k}{t}$ the number of t column projections that can be obtained from k columns.

$$t_{\mathcal{A}}\text{Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i.$$

$$t_{\mathcal{A}}\text{Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r.$$

Note: $p_i = \prod_{k=1}^t v_{f(k)}$ where $f(k)$ is the k^{th} column of the i^{th} projection.

¹S. Dalal & C. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

Covering arrays - Preliminaries

t -Coverage:

The ratio of the number of distinct t tuples, to the number of **possible** t tuples, averaged over all t column projections ($1 \leq t \leq K$).

t -Diversity:

The ratio of the number of distinct t tuples, to the **total** number of t tuples, averaged over all t column projections ($1 \leq t \leq K$).

Covering arrays - Preliminaries

t -Coverage =

t -Diversity =

Covering arrays - Preliminaries

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r$$

1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

CA(6; 2, 5, 2)

Covering arrays - Preliminaries

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r$$

1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

CA(6; 2, 5, 2)

<i>t</i>	Coverage	Diversity
2	100.0	66.7
3	70.0	93.3
4	37.5	100.0

Covering arrays - Preliminaries

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r$$

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

CA(12; 3, 5, 2)

Covering arrays - Preliminaries

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r_i$$

t	Coverage	Diversity
3	100.0	66.7
4	70.0	93.3
5	37.5	100.0

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

CA(12; 3, 5, 2)

Covering arrays - Preliminaries

t -Coverage =

t -Diversity =

Covering arrays - Preliminaries

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r_i$$

Air to ground missile system, **CA**(6; 2, 10, 2):

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	1	1	1	1	1	1
1	1	1	1	2	2	2	2	2	2
1	2	2	2	1	1	1	2	2	2
2	1	2	2	1	2	2	1	1	2
2	2	1	2	2	1	2	1	2	1
2	2	2	1	2	2	1	2	1	1

Covering arrays - Preliminaries

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r_i$$

Air to ground missile system, **CA(6; 2, 10, 2):**

t	Coverage	Diversity
2	100.0	66.7
3	68.8	91.7
4	37.1	98.8

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
1	1	1	1	1	1	1	1	1	1
1	1	1	1	2	2	2	2	2	2
1	2	2	2	1	1	1	2	2	2
2	1	2	2	1	2	2	1	1	2
2	2	1	2	2	1	2	1	2	1
2	2	2	1	2	2	1	2	1	1

Covering arrays - Preliminaries

Definition

A *mixed level covering array* **MCA**($N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_k)$) is an $N \times k$ array such that the i -th column contains v_i distinct symbols. If for any t coordinate projection, all $\prod v_i$ combinations of symbols exist, then it is a **t -covering array** and is optimal if N is minimal for fixed t , k , and $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$.

Covering arrays - Preliminaries

Definition

A *mixed level covering array* **MCA**($N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_k)$) is an $N \times k$ array such that the i -th column contains v_i distinct symbols. If for any t coordinate projection, all $\prod v_i$ combinations of symbols exist, then it is a **t -covering array** and is optimal if N is minimal for fixed t , k , and $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$.

1	1	2	2	2
1	2	2	2	1
1	3	1	1	1
2	1	1	2	1
2	2	1	1	2
2	3	2	1	1
3	1	1	1	2
3	2	2	1	1
3	3	2	2	2

Covering arrays - Preliminaries

Definition

A *mixed level covering array* **MCA**($N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_k)$) is an $N \times k$ array such that the i -th column contains v_i distinct symbols. If for any t coordinate projection, all $\prod v_i$ combinations of symbols exist, then it is a t -covering array and is optimal if N is minimal for fixed t , k , and $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$.

An optimal **MCA**(9; 2, $(3^2 \cdot 2^3)$).

1	1	2	2	2
1	2	2	2	1
1	3	1	1	1
2	1	1	2	1
2	2	1	1	2
2	3	2	1	1
3	1	1	1	2
3	2	2	1	1
3	3	2	2	2

Covering arrays - Preliminaries

Definition

A *mixed level covering array* **MCA**($N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_k)$) is an $N \times k$ array such that the i -th column contains v_i distinct symbols. If for any t coordinate projection, all $\prod v_i$ combinations of symbols exist, then it is a **t -covering array** and is optimal if N is minimal for fixed t , k , and $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$.

t	Coverage	Diversity
2	100.0	63.3
3	65.0	93.3
4	30.0	100.0

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i.$$

$$t\text{-Diversity} = \frac{1}{M} \sum_{i=1}^M n_i / r.$$

1	1	2	2	2
1	2	2	2	1
1	3	1	1	1
2	1	1	2	1
2	2	1	1	2
2	3	2	1	1
3	1	1	1	2
3	2	2	1	1
3	3	2	2	2

MCA(9; 2, (3² · 2³))

Covering arrays - Preliminaries

Covering arrays - Preliminaries

In practice, systems and software validation problems come with constraints. Consider a GUI that contains a variety of controls, such as checkboxes, combo boxes, etc., where some setting of a particular control precludes settings of some other control.

In discussing testing configurable systems, Myra Cohen¹ makes the point:

“Constraints may arise due to any number of reasons, for example, inconsistencies between certain hardware components, limitations due to available memory and software size, or simply marketing decisions.”

Constraints are sometimes referred to as *disallowed combinations* or *forbidden interactions*.

¹M. Cohen, M. Dwyer, J. Shi, “Interaction testing of highly-configurable systems in the presence of constraints,” IEEE TSE, 2008, 633-650.

Covering arrays - Preliminaries

MCA's are not sufficient, we need another generalization!

Constrained covering arrays

Definition¹

A *constrained covering array* **CCA**(N ; t , $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$, ϕ) is an $N \times k$ array such that the i -th column contains v_i distinct symbols and ϕ is a set of p -tuples ($2 \leq p \leq k$) such that each tuple is a set of two or more column/value pairs identifying a disallowed combination. If for any t coordinate projection, all **possible** combinations of symbols exist, then it is a t -covering array and is optimal if N is minimal for fixed t , k , $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$, and ϕ .

Note: Let us say that the symbol set for columns c_1 and c_2 is $\{1, 2\}$ and the symbol combination $(2, 1)$ is not allowed then $\phi = \{(c_1, 2), (c_2, 2)\}$.

¹J. Morgan, "Combinatorial Testing: An approach to systems and software testing based on covering arrays," in *Analytic Methods in Systems and Software Testing*, eds., F. Ruggeri, R. Kennett, & F. Faltin, Wiley, 2018.

Constrained covering arrays

Consider a **CCA**(9; 2, $(3^2 \cdot 2^3), \phi$) where $\phi = \{(c_1, 1), (c_3, 1)\}$.

It is usually convenient to express ϕ more compactly. Cohen¹, suggests a shorthand exponent notation, p^k , to indicate k p -tuples. In this case, $\phi = \{2^1\}$.

¹M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

Constrained covering arrays

Consider a **CCA**(9; 2, $(3^2 \cdot 2^3), \phi$) where $\phi = \{(c_1, 1), (c_3, 1)\}$.

It is usually convenient to express ϕ more compactly. Cohen¹, suggests a shorthand exponent notation, p^k , to indicate k p -tuples. In this case, $\phi = \{2^1\}$.

c	c	c	c	c
1	1	2	2	1
1	2	2	1	2
1	3	2	2	2
2	1	1	2	2
2	2	2	2	2
2	3	2	1	1
3	1	2	1	1
3	2	1	2	1
3	3	1	1	2

CCA(9; 2, $(3^2 \cdot 2^3), \phi = \{2^1\}$)

Optimal

Exponent notation

¹M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

Case Study #2

Mobile Phone Configuration

Constrained covering arrays

Consider a mobile phone configuration problem (Cohen et al.¹):

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

¹M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

Covering arrays - Phone constraints¹

- I. Graphical email viewer **requires** a color display.
- II. 2 megapixel camera **requires** a color display.
- III. Graphical email viewer is **not supported** with 2 megapixel cameras.
- IV. 8 million color display **does not support** a 2 megapixel camera.
- V. Video camera **requires** a camera and a color display.
- VI. Video ringtones **cannot occur** without a video camera.
- VII. 16 million colors, text, and 2 megapixel camera **not supported**.

¹M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

Covering arrays - Phone constraints¹

- I. Graphical email viewer **requires** a color display.
- II. 2 megapixel camera **requires** a color display.
- III. Graphical email viewer is **not supported** with 2 megapixel cameras.
- IV. 8 million color display **does not support** a 2 megapixel camera.
- V. Video camera **requires** a camera and a color display.
- VI. Video ringtones **cannot occur** without a video camera.
- VII. 16 million colors, text, and 2 megapixel camera **not supported**.

¹M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

Covering arrays - Disallowed combinations

I. Display: B&W, Email Viewer: Graphical.

II. Display: B&W, Camera: 2 megapixel.

III. Email Viewer: Graphical, Camera: 2 megapixel.

IV. Display: 8 million colors, Camera: 2 megapixel.

V. (Display: B&W, Video Camera: Y) & (Camera: None, Video Camera: Y).

VI. Video Camera: N, Video Ringtones: N.

VII. Display: 16 million colors, Email Viewer: Text, Camera: 2 megapixel.

Constrained covering arrays - Phone example

$CCA(10; 2, (3^3 \cdot 2^2), \phi = \{2^7 \cdot 3^1\})$

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

Constrained covering arrays - Phone example

$CCA(10; 2, (3^3 \cdot 2^2), \phi = \{2^7 \cdot 3^1\})$

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), $\phi = \{2^7 \cdot 3^1\}$)



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Disallowed combination:

Display: B&W,

Email Viewer: Graphical

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), $\phi = \{2^7 \cdot 3^1\}$)



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

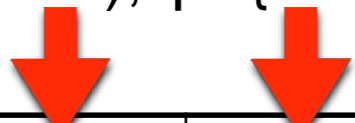
Disallowed combination:

Display: B&W, **Camera:** 2MP

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), φ = {2⁷·3¹})



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Disallowed combination:

Email Viewer: Graphical,

Camera: 2MP

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), $\phi = \{2^7 \cdot 3^1\}$)



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Disallowed combination:

Display: 8 mill, **Camera:** 2MP

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), $\phi = \{2^7 \cdot 3^1\}$)



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Disallowed combination:

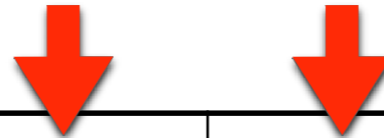
(**Display:** B&W, **Video Camera:** Y) &

(**Camera:** None, **Video Camera:** Y)

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), φ = {2⁷·3¹})



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Disallowed combination:

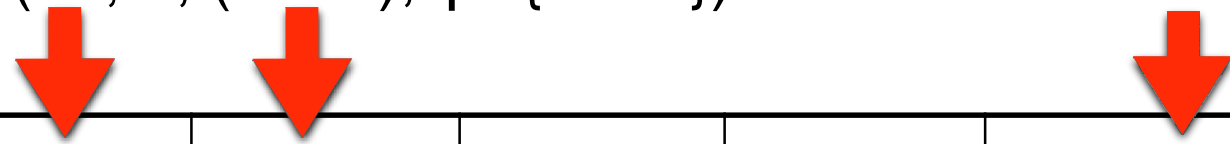
Video Camera: N,

Video Ringtones: N

Constrained covering arrays - Phone example

Component	Setting
Display	16 million colors 8 million colors Black & White
Email viewer	Graphical Text None
Camera	2 Megapixel 1 Megapixel None
Video Camera	Yes No
Video Ringtones	Yes No

CCA(10; 2, (3³·2²), $\phi = \{2^7 \cdot 3^1\}$)



Display	Email Viewer	Camera	Video Camera	Video Ringtones
16 mill	Graphical	None	N	N
16 mill	Text	2MP	N	N
16 mill	None	2MP	Y	Y
16 mill	Graphical	1MP	Y	Y
8 mill	Graphical	1MP	N	N
8 mill	Text	1MP	Y	Y
8 mill	Text	None	N	N
8 mill	None	1MP	Y	N
B&W	Text	1MP	N	N
B&W	None	None	N	N

Disallowed combination:

Display: 16 mill,

Email Viewer: Text,

Camera: 2MP

Constrained covering arrays - Examples¹

1. Bugzilla 2.22.2:

- 1.1. Bugzilla is an open source defect tracking system from Mozilla.
- 1.2. From the *Administering Bugzilla, Using Bugzilla, and Customizing Bugzilla* chapters, 5 constraints involving 11 options were found.
- 1.3. We need a **CCA**(N; t, $(2^{49} \cdot 3^1 \cdot 4^2)$, $\phi = \{2^4 \cdot 3^1\}$) design. The unconstrained configuration space is 2.7×10^{16} .
e.g.: When “Mail Transfer Agent” is “Postfix”, “sendmailnow” option must be on.

2. GCC 4.1 - Optimizer only:

1. GCC is a compiler infrastructure with support for multiple languages (e.g. C, C++, Ada) and over 30 different target machine architectures.
2. From the documentation, 40 constraints involving 35 options were found.
3. We need a **CCA**(N; t, $(2^{189} \cdot 3^{10})$, $\phi = \{2^{37} \cdot 3^3\}$) design. The unconstrained configuration space is 4.6×10^{61} .

¹M. Cohen, M. Dwyer, J. Shi, “Interaction testing of highly-configurable systems in the presence of constraints,” IEEE TSE, 2008, 633-650.

Constrained covering arrays - Examples¹

1. **Bugzilla 2.22.2:** For $t=2$, C-CAN =
16

1.1. Bugzilla is an open source defect tracking system from Mozilla.

1.2. From the *Administering Bugzilla, Using Bugzilla, and Customizing Bugzilla* chapters, 5 constraints involving 11 options were found.

1.3. We need a **CCA**($N; t, (2^{49} \cdot 3^1 \cdot 4^2), \phi = \{2^4 \cdot 3^1\}$) design. The unconstrained configuration space is 2.7×10^{16} .

e.g.: When “Mail Transfer Agent” is “Postfix”, “sendmailnow” option must be on.

2. **GCC 4.1 - Optimizer only:** For $t=2$, C-CAN \leq
20

1. GCC is a compiler infrastructure with support for multiple languages (e.g. C, C++, Ada) and over 30 different target machine architectures.

2. From the documentation, 40 constraints involving 35 options were found.

3. We need a **CCA**($N; t, (2^{189} \cdot 3^{10}), \phi = \{2^{37} \cdot 3^3\}$) design. The unconstrained configuration space is 4.6×10^{61} .

¹M. Cohen, M. Dwyer, J. Shi, “Interaction testing of highly-configurable systems in the presence of constraints,” IEEE

Constrained covering arrays

Constrained covering arrays

As defined CCA's are still not sufficient!

Constrained covering arrays

Consider a **CCA**(9; 2, $(3^2 \cdot 2^3), \phi$) where $\phi = \{\{(c_1, 1), (c_3, 1)\}, \{(c_1, 1), (c_3, 2)\}\}$.

Constrained covering arrays

Consider a **CCA**(9; 2, $(3^2 \cdot 2^3), \phi$) where $\phi = \{ \{(c_1, 1), (c_3, 1)\}, \{(c_1, 1), (c_3, 2)\} \}$.

c	c	c	c	c
1	1	.	1	1
1	2	.	2	2
1	3	.	2	1
2	1	1	2	1
2	2	2	1	1
2	3	2	1	2
3	1	2	2	2
3	2	1	1	1
3	3	1	2	2

CCA(9; 2, $(3^2 \cdot 2^3), \phi = \{2^2\}$)

Constrained covering arrays

Consider a **CCA**(9; 2, $(3^2 \cdot 2^3), \phi$) where $\phi = \{ \{(c_1, 1), (c_3, 1)\}, \{(c_1, 1), (c_3, 2)\} \}$.

c	c	c	c	c
1	1	.	1	1
1	2	.	2	2
1	3	.	2	1
2	1	1	2	1
2	2	2	1	1
2	3	2	1	2
3	1	2	2	2
3	2	1	1	1
3	3	1	2	2

CCA(9; 2, $(3^2 \cdot 2^3), \phi = \{2^2\}$)

Optimal

Constrained covering arrays

Consider a **CCA**(9; 2, $(3^2 \cdot 2^3), \phi$) where $\phi = \{ \{(c_1, 1), (c_3, 1)\}, \{(c_1, 1), (c_3, 2)\} \}$.

When c_1 is set to 1 there are no allowable settings for column c_3 . The symbol “.” is used to indicate an unassigned cell.

Note: We refer to such covering arrays as *unsatisfiable* constrained covering arrays.

c	c	c	c	c
1	1	.	1	1
1	2	.	2	2
1	3	.	2	1
2	1	1	2	1
2	2	2	1	1
2	3	2	1	2
3	1	2	2	2
3	2	1	1	1
3	3	1	2	2

CCA(9; 2, $(3^2 \cdot 2^3), \phi = \{2^2\}$)

Optimal

Constrained covering arrays

Definition¹

Consider $\mathcal{A} = \mathbf{CCA}(N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_k), \phi)$. For the i^{th} projection, let n_i be the number of distinct t tuples, p_i the number of possible t tuples, a_i the number of invalid t tuples, $M' = \kappa C_t - m$, (m the number of projections where there are no valid t tuples), and $r_i = r - q_i$, (q_i the number of rows with missing values).

$$\text{Adjusted } t_{\mathcal{A}}\text{-Coverage} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / (p_i - a_i)$$

$$\text{Adjusted } t_{\mathcal{A}}\text{-Diversity} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / r_i$$

¹J. Morgan, "Combinatorial Testing: An approach to systems and software testing based on covering arrays," in *Analytic Methods in Systems and Software Testing*, eds., F. Ruggeri, R. Kennett, & F. Faltin, Wiley, 2018.

Constrained covering arrays

Adjusted t_A -Coverage:

The ratio of the number of distinct t tuples, to the number of **adjusted possible** t tuples, averaged over all t column projections ($1 \leq t \leq K$) that contain valid tuples.

Adjusted t_A -Diversity:

The ratio of the number of distinct t tuples, to the **adjusted total** number of t tuples, averaged over all t column projections ($1 \leq t \leq K$) that contain valid tuples.

Constrained covering arrays

$$\text{Adjusted } t\text{-Coverage} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / (p_i - a_i)$$

$$\text{Adjusted } t\text{-Diversity} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / r_i$$

Constrained covering arrays

$$\text{Adjusted } t\text{-Coverage} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / (p_i - a_i)$$

$$\text{Adjusted } t\text{-Diversity} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / r_i$$

c	c	c	c	c
1	1	2	2	1
1	2	2	1	2
1	3	2	2	2
2	1	1	2	2
2	2	2	2	2
2	3	2	1	1
3	1	2	1	1
3	2	1	2	1
3	3	1	1	2

CCA(9; 2, (3²·2³), $\phi = \{2^1\}$)

Constrained covering arrays

$$\text{Adjusted } t\text{-Coverage} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / (p_i - a_i)$$

$$\text{Adjusted } t\text{-Diversity} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / r_i$$

c	c	c	c	c
1	1	2	2	1
1	2	2	1	2
1	3	2	2	2
2	1	1	2	2
2	2	2	2	2
2	3	2	1	1
3	1	2	1	1
3	2	1	2	1
3	3	1	1	2

CCA(9; 2, (3²·2³), $\phi = \{2^1\}$)

<i>t</i>	Adjusted Coverage	Adjusted Diversity
2	100.0	62.2
3	68.3	92.2
4	33.5	100.0

Constrained covering arrays

$$\text{Adjusted } t\text{-Coverage} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / (p_i - a_i)$$

$$\text{Adjusted } t\text{-Diversity} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / r_i$$

c	c	c	c	c
1	1	.	1	1
1	2	.	2	2
1	3	.	2	1
2	1	1	2	1
2	2	2	1	1
2	3	2	1	2
3	1	2	2	2
3	2	1	1	1
3	3	1	2	2

CCA(9; 2, (3²·2³), $\phi = \{2^2\}$)

Constrained covering arrays

$$\text{Adjusted } t\text{-Coverage} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / (p_i - a_i)$$

$$\text{Adjusted } t\text{-Diversity} = \frac{1}{M'} \sum_{i=1}^{M'} n_i / r_i$$

t	Adjusted Coverage	Adjusted Diversity
2	100.0	71.1
3	59.6	96.1
4	27.5	100.0

c	c	c	c	c
1	1	.	1	1
1	2	.	2	2
1	3	.	2	1
2	1	1	2	1
2	2	2	1	1
2	3	2	1	2
3	1	2	2	2
3	2	1	1	1
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CCA(9; 2, (3²·2³), $\phi = \{2^2\}$)

Covering arrays - Software Validation

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Question: Are covering arrays effective tools for deriving test suites to validate software systems?

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Answer: Kuhn et al.¹ examined several classes of software systems and discovered the following:

	% faults detected			
	t=2	t=3	t=4	t=5
Medical device software	95	99	100	100
Browser application	70	90	95	96
Server software	75	95	96	99
Network security	62	89	99	100
TCAS	54	74	89	100

Only 3600 test cases, < 1% of exhaustive testing!

¹D. Kuhn & D. Wallace, & A. Gallo, "Software fault interactions and implications for software testing," IEEE Trans. SE, v30(6) (2004), 418-421.

Covering arrays - Software Validation

Takeaway:

- Given a software system with k inputs, a strength t covering array may be used to generate a test suite in which all t -way interactions are covered by at least one test case. If $t \ll k$ then the cost savings is dramatic when compared to exhaustive testing.
- Covering arrays are an effective and efficient tool for deriving test suites to validate software systems.

Covering arrays - Software Validation

Takeaway:

- Given a software system with k inputs, a strength t covering array may be used to generate a test suite in which all t -way interactions are covered by at least one test case. If $t \ll k$ then the cost savings is dramatic when compared to exhaustive testing.
- Covering arrays are an effective and efficient tool for deriving test suites to validate software systems.

*Pseudo-exhaustive testing*¹

¹D. Kuhn & V. Okum, "Pseudo-exhaustive testing for software," Proc. 30th IEEE/NASA Software Engineering Workshop, (2006).

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Thank You